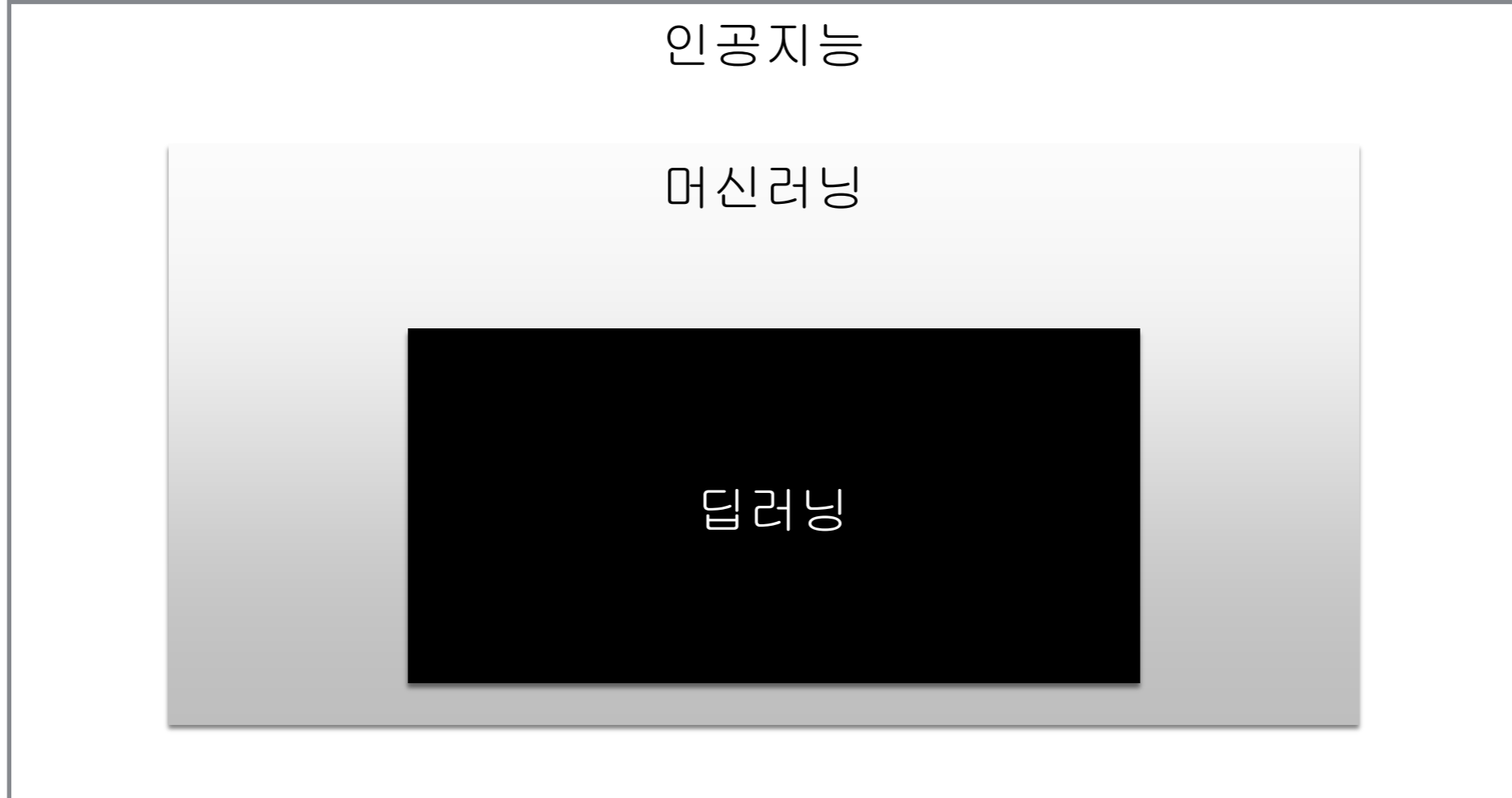


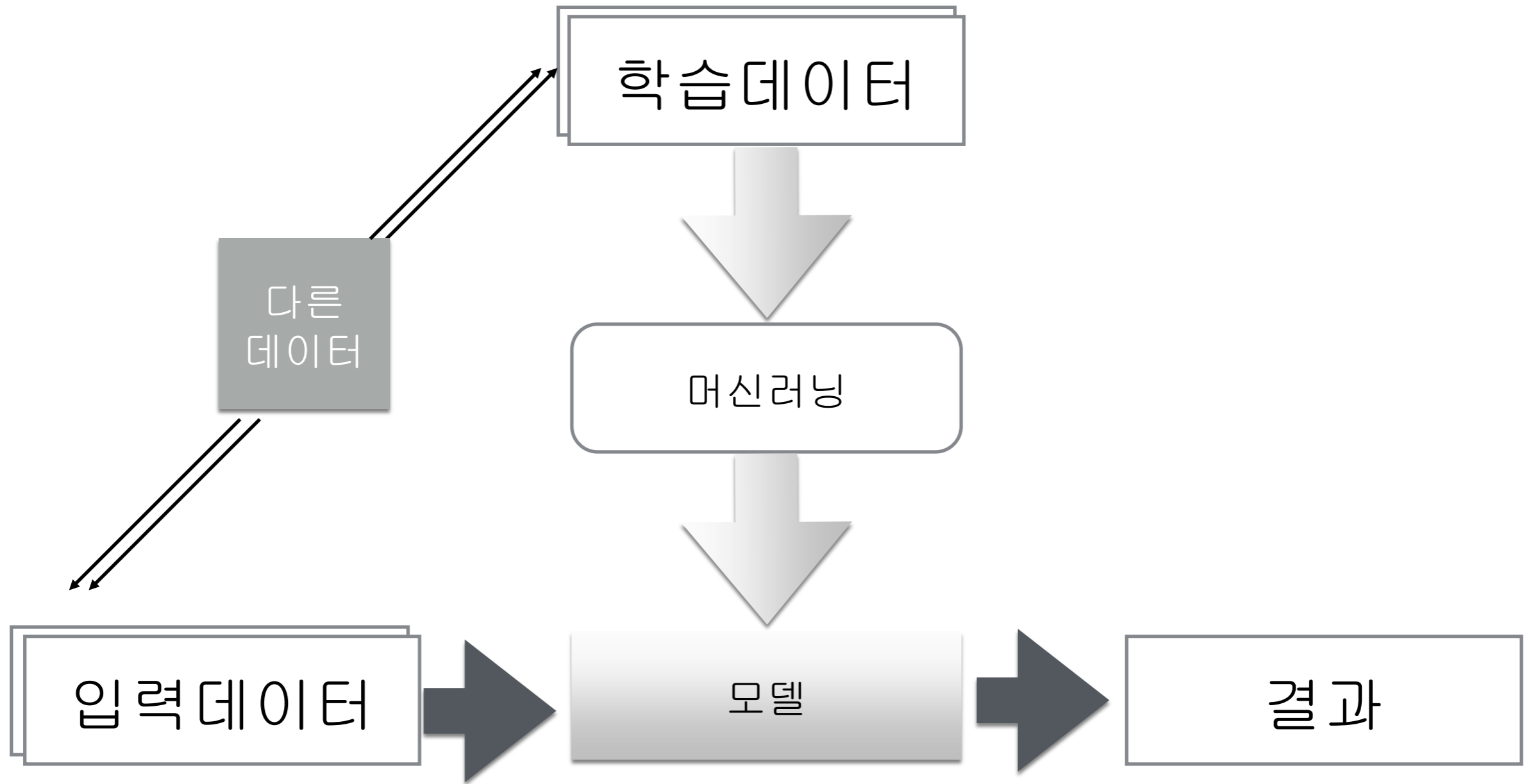
딥러닝 첫걸음

1. 머신러닝



인공지능, 머신러닝, 딥
러닝

머신러닝



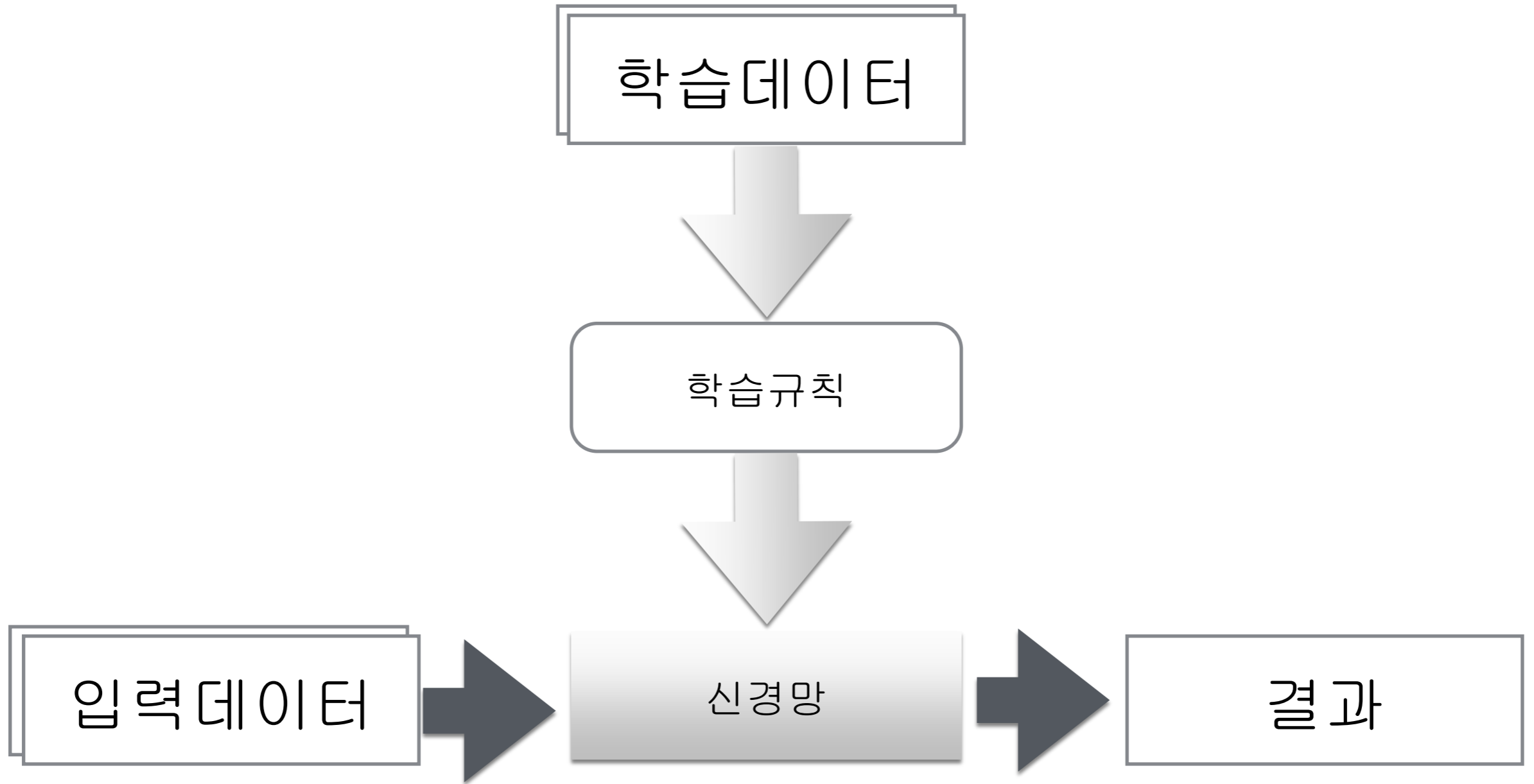
과적합, 정칙화, 검증

- 과적합(Overfitting) : Sample 추정에 지나치게 특화되어
새로운 Sample 추정 성과가 나빠지는 현상
 - 지나치게 많은 설명변수를 사용할 경우 자주 발생
- 정칙화(Regularization) : 설명변수의 수를 줄이려는 시도
- 검증(Validation): Sample 을 추정용(train)/ 검증용(test) 으로 나누고, 추정용으로 학습한 모형의 성과를 검증용으로 점검

머신러닝 종류

- 학습 방식에 따라: 지도학습, 비지도학습, 강화학습
 - 지도학습: 정답이 있는 입력자료 사용하여 모형의 결과와 정답간의 차이를 줄이는 학습
 - 비지도학습: 정답이 없는 입력자료를 사용하여 패턴에 따라 분류하는 학습
 - 강화학습:?
- 모델의 쓰임새?: 회귀(Regression), 분류(Categorization)
 - 회귀: 추세예측/분류: 범주예측

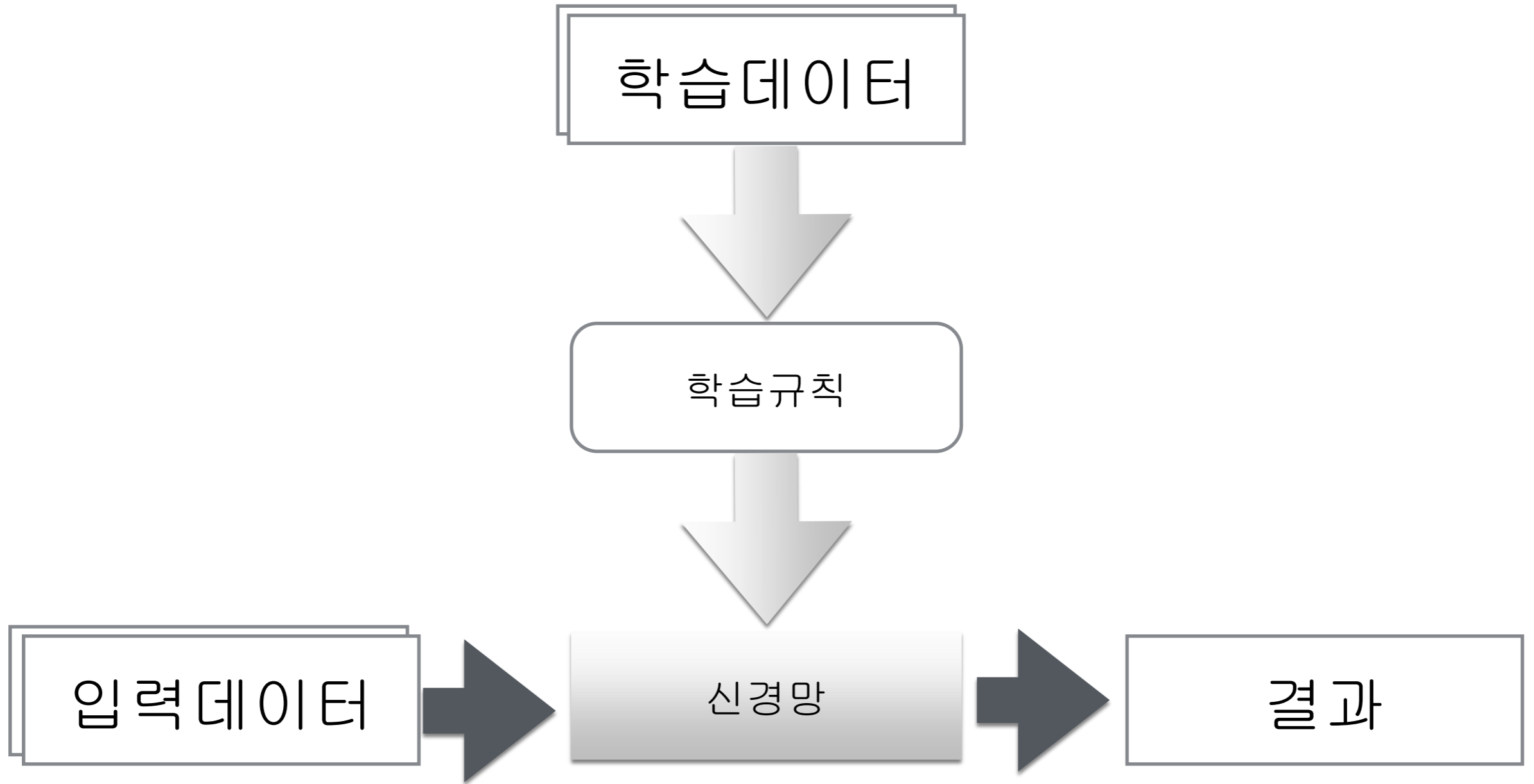
딥러닝



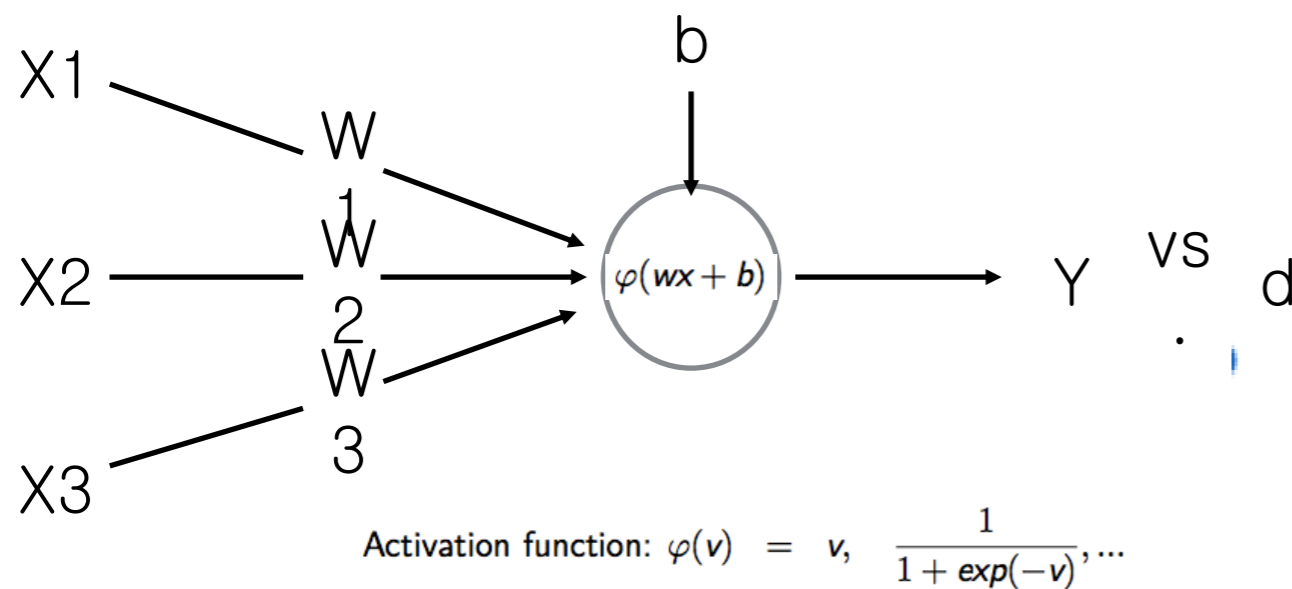
딥러닝 첫걸음

2. 신경망

딥러닝



Node



$$\text{weight : } w = [w_1, w_2, w_3]$$

$$\text{input : } x = [x_1, x_2, x_3]^T$$

$$\text{weighted sum : } v = w_1x_1 + w_2x_2 + w_3x_3 + b$$
$$wx + b$$

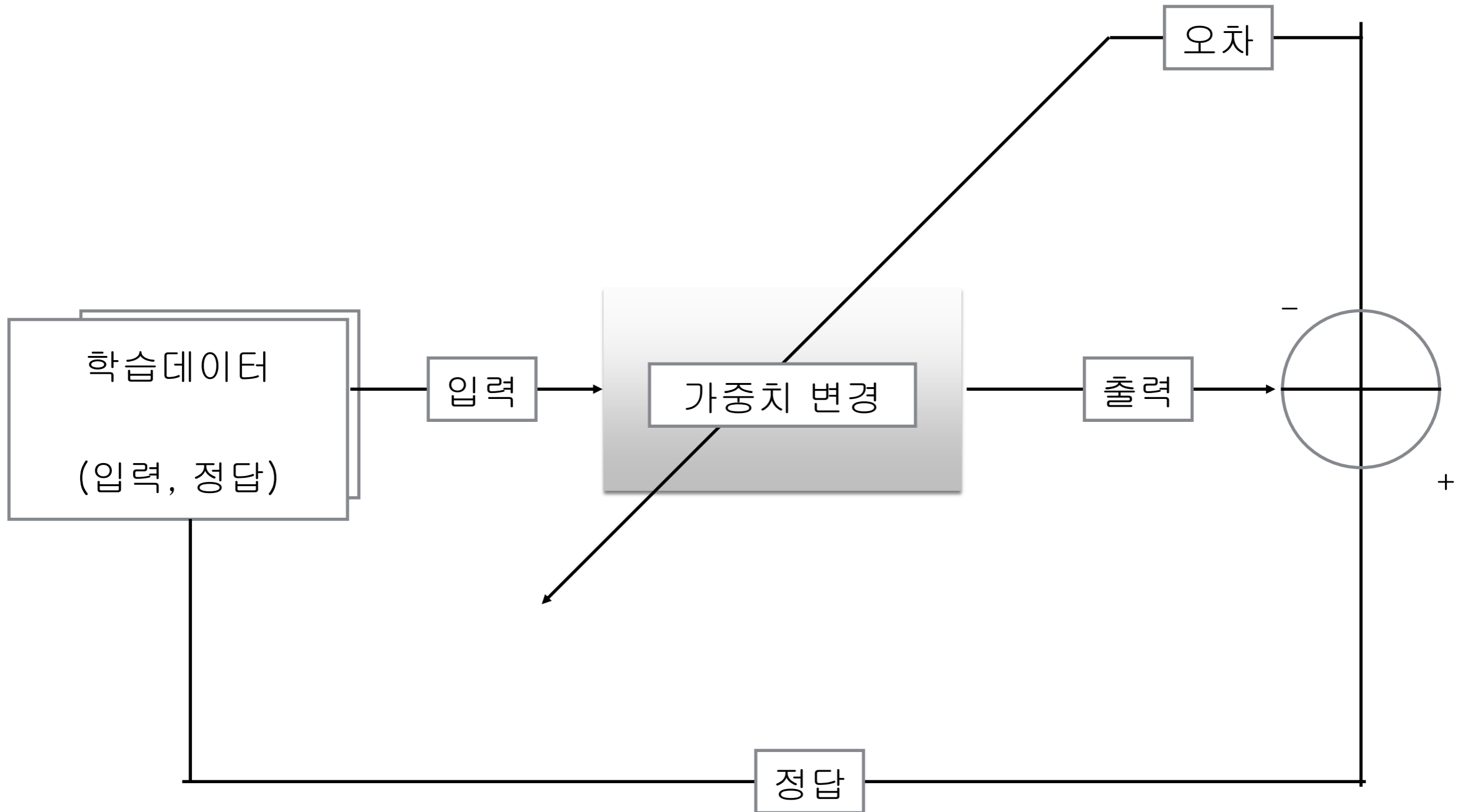
$$\text{output : } y = \varphi(v) = \varphi(wx + b)$$

$$\text{Activation function : } \varphi(v) = v, \frac{1}{1 + \exp(-v)}, \dots$$

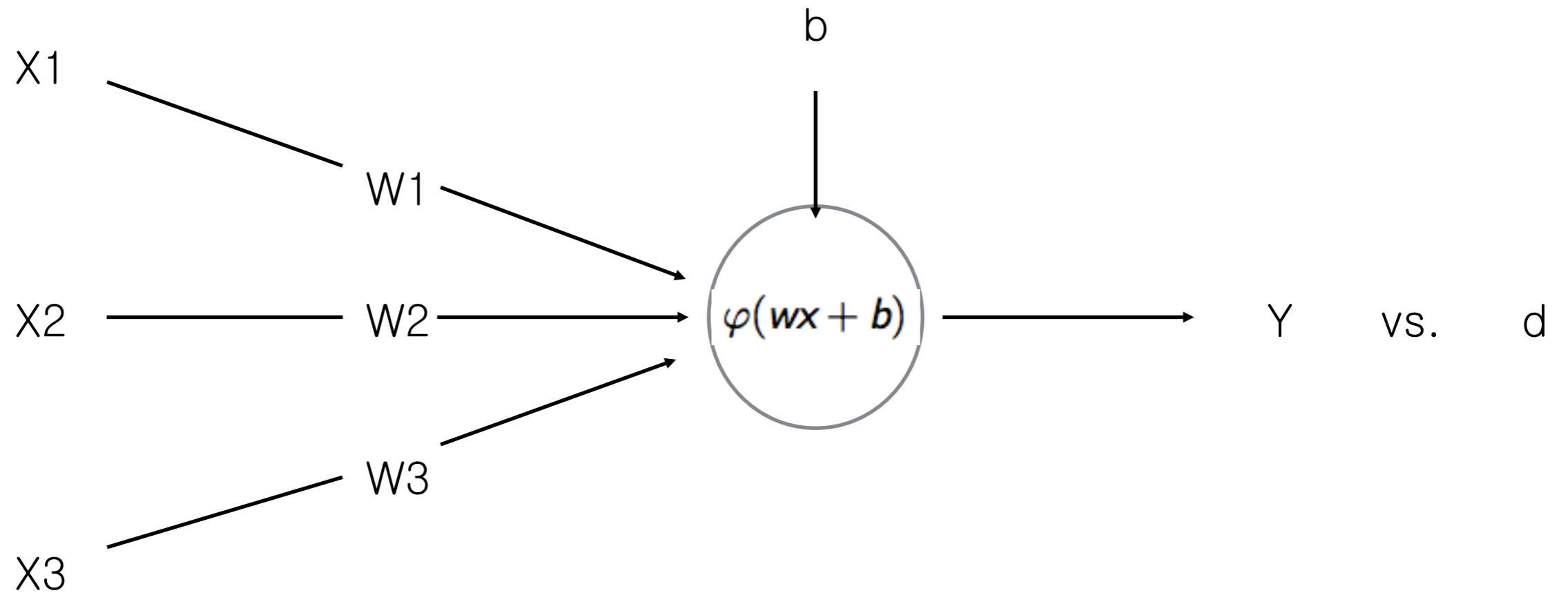
신경망 지도학습

1. 가중치 초기화
2. 입력 데이터 => 결과
3. 오차 = 결과 - 정답
4. 가중치 조정 : 오차 축소
5. 2-4. 반복

신경망 지도학습

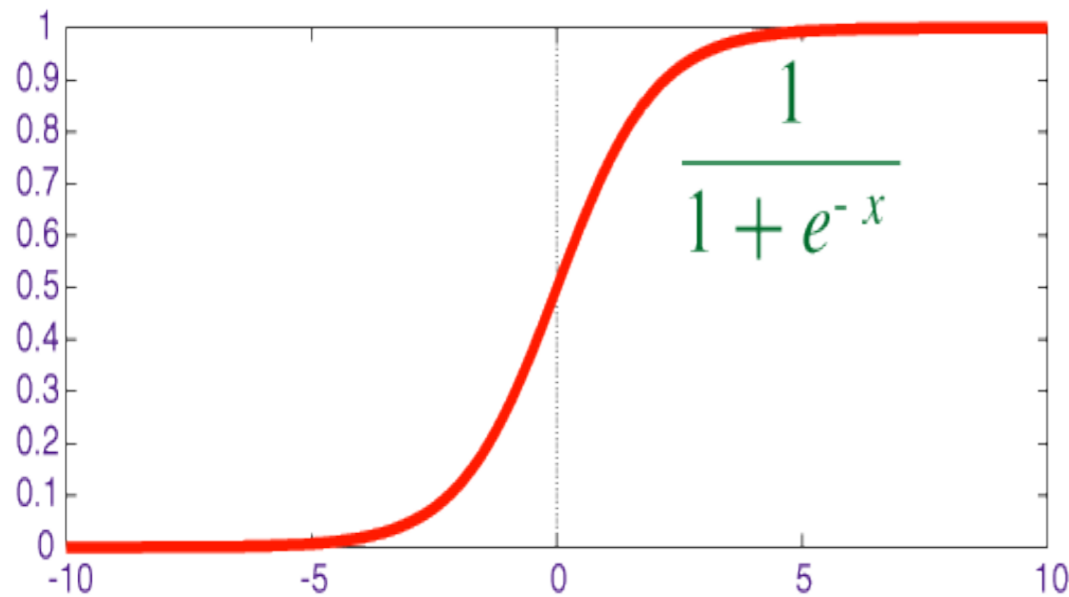


단층 신경망



Activation function: $\varphi(v) = v, \frac{1}{1 + \exp(-v)}, \dots$

Sigmoid function



$$\begin{aligned}\varphi(v) &= \frac{1}{1 + \exp(-v)} \\ \varphi'(v) &= -1 \times \frac{-\exp(-v)}{(1 + \exp(-v))^2} = \times \frac{\exp(-v)}{(1 + \exp(-v))^2} \\ &= \frac{1}{1 + \exp(-v)} \times \frac{\exp(-v)}{1 + \exp(-v)} \\ &= \frac{1}{1 + \exp(-v)} \times \left[1 - \frac{1}{1 + \exp(-v)} \right] \\ &= \varphi(v)(1 - \varphi(v))\end{aligned}$$

단층신경망 학습: 델타 규칙

1. 가중치 초기화:

$$w^0 = [w_{11}^0, w_{12}^0, w_{13}^0]$$

2. 입력데이터 → 결과:

$$x = [x_1, x_2, x_3]^T$$

$$v_1^0 = w_{11}^0 x_1 + w_{12}^0 x_2 + w_{13}^0 x_3 + b^0 = w^0 x + b^0$$

$$y_1^0 = \varphi(v_1^0) = \varphi(w^0 x + b^0)$$

3. 오차 = 결과 - 정답

$$e_1^0 = d_1 - y_1^0$$

4. 가중치 조정: 오차 축소

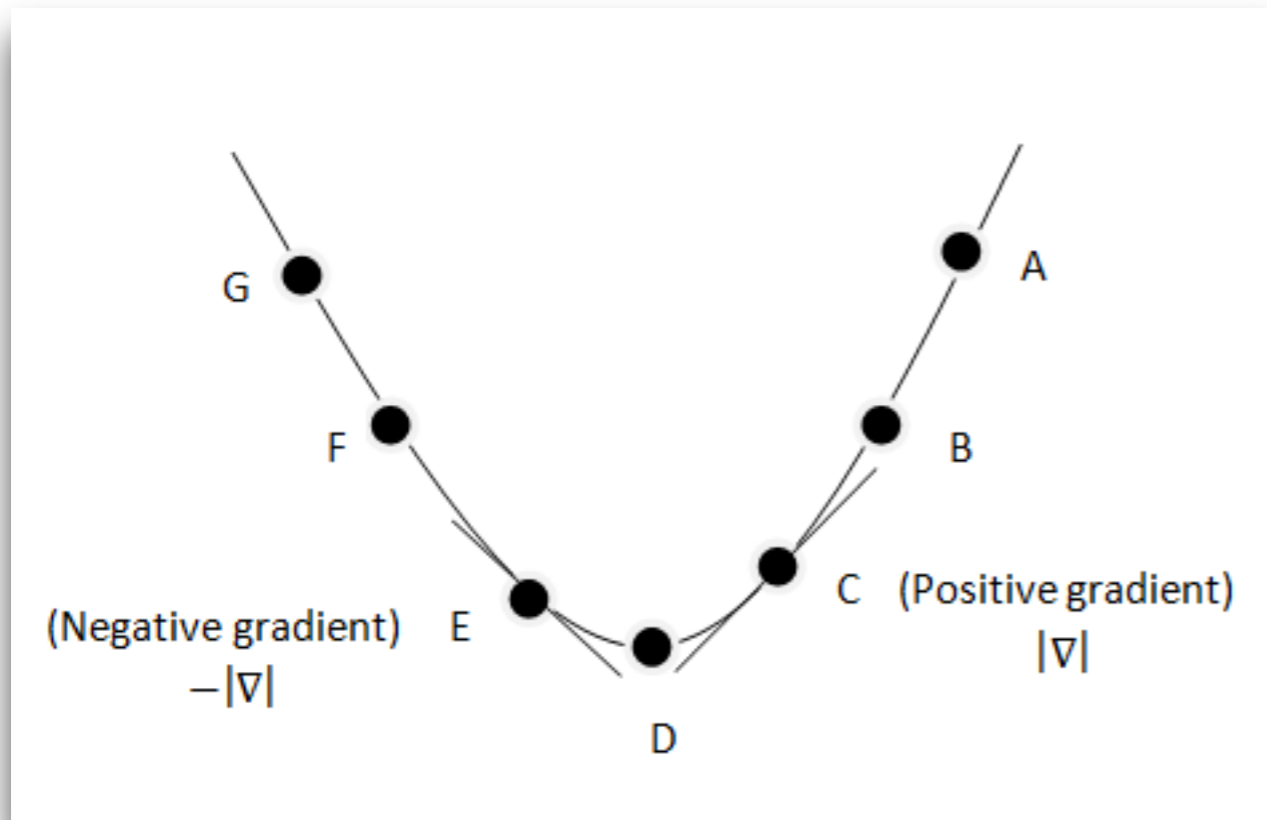
$$\delta_1^0 = \varphi'(v_1^0) e_1^0 = e_1^0 \quad (\varphi'(v_1^0) = 1)$$

$$w_{11}^1 = w_{11}^0 + \alpha \delta_1^0 x_1$$

$$w_{12}^1 = w_{11}^0 + \alpha \delta_1^0 x_2$$

$$w_{13}^1 = w_{11}^0 + \alpha \delta_1^0 x_3$$

Gradient Descent



$$\begin{aligned} J &= (d - y)^2 = (d - \varphi(v))^2 = (d - \varphi(wx))^2 \\ \frac{\partial J}{\partial w_i} &= -2(d - \varphi(wx))\varphi'(wx)x_i \\ &= -2e\varphi'(wx)x_i = -2\delta x_i \\ \alpha\delta x_i &\propto -\frac{\partial J}{\partial w_i} \end{aligned}$$

training function

```
function W = Deltasgd (W,X,D)
alpha=0.9;
N=4;
  for k=1:N

2. 입력데이터 -> 결과
  x=X(k,:);
  d=D(k);
  v=W*x;
  y=Sigmoid(v);

3. 오차 = 결과 - 정답
  e=d-y;

4. 가중치 조정 ( k loop 안에서)
  delta=y*(1-y)*e;
  dW=alpha*delta*x;
  W(1)=W(1)+dW(1);
  W(2)=W(2)+dW(2);
  W(3)=W(3)+dW(3);
  end
end
```

```
function W = Deltabatch(W,X,D)
alpha=0.9;
dWSum=zeros(3,1);

N=4;
  for k=1:N

2. 입력데이터 -> 결과
  x=X(k,:);
  d=D(k);
  v=W*x;
  y=Sigmoid(v);

3. 오차 = 결과 - 정답
  e=d-y;

4. 가중치 조정
  delta=y*(1-y)*e;
  dW=alpha*delta*x;
  dWSum=dWSum+dW;
  end
(가중치 조정은 k 루프가 끝난 다음)
  dWAvg=dWSum/N;

  W(1)=W(1)+dWAvg(1);
  W(2)=W(2)+dWAvg(2);
  W(3)=W(3)+dWAvg(3);
  end
```

Sigmoid function: Sigmoid.m

```
function y=Sigmoid(x)
```

```
    y=1./(1+exp(-x));
```

```
end
```

SGD, batch training function

```
function W = Deltasgd (W,X,D)
% setting learning rate
alpha=0.9;
% applying delta method for each
observation
N=4;
for k=1:N
%% input and outputdata on kth
observation
x=X(k,:)' ;
d=D(k);
%% obtain weighted sum of input
v=W*x;
%% obtain output
y=Sigmoid(v);
%% obtain error
e=d-y;
%% obtain delta =d of activation function *
error
delta=y*(1-y)*e;
%% obtain adjustment term
dW=alpha*delta*x;
%% update weight: add adjustment terms to
weight.
W(1)=W(1)+dW(1);
W(2)=W(2)+dW(2);
W(3)=W(3)+dW(3);
end
```

```
function W = Deltabatch(W,X,D)
% setting learning rate
alpha=0.9;
%set up a variable to save sum of weight adjustments
dWSum=zeros(3,1);
%applying delta method one time for all sample
N=4;
%% input and outputdata on kth observation
for k=1:N
x=X(k,:)' ;
d=D(k);
%% obtain weighted sum of input
v=W*x;
%% obtain output
y=Sigmoid(v);
%% obtain error
e=d-y;
%% obtain delta =d of activation function * error
delta=y*(1-y)*e;
%% obtain weight adjustment term
dW=alpha*delta*x;
%% add up weight adjustment term
dWSum=dWSum+dW;
end
% take average of sum of weight adjustment
dWAvg=dWSum/N;
% weight adjustment
W(1)=W(1)+dWAvg(1);
W(2)=W(2)+dWAvg(2);
W(3)=W(3)+dWAvg(3);
end
```

TestDelat**.m (학습)

```
%Clearing memory
clear all
%Declaring input and output data
X=[0, 0, 1; 0, 1, 1; 1, 0, 1; 1, 1, 1];
D=[0,0,1,1];
%initialize weight
W=2*rand(1,3)-1;
%train model
for epoch=1:10000
W=Deltasgd(W,X,D);
%W=DeltasgdM(W,X,D);
end
%obtain estimate
y=Sigmoid(X*W')
%N=4;
%for k=1:N
%x=X(k,:)'
%v=W*x;
%y=Sigmoid(v)
%end
```

```
clear all
X=[0, 0, 1; 0, 1, 1; 1, 0, 1; 1, 1,
1];
D=[0,0,1,1];
rand('seed',1);
W=2*rand(1,3)-1;

for epoch=1:1000000
%W=Deltasgd(W,X,D);
%W=Deltabatch(W,X,D);
W=DeltabatchM(W,X,D);
end

y=Sigmoid(X*W')
%N=4;
%for k=1:N
%x=X(k,:)'
%v=W*x;
%y=Sigmoid(v)
%end
```

실습 1. Matlab => R

- Sigmoid.m
- Deltasgd.m
- Deltabatch.m
- Testdeltabatch.m
- Testdeltasgd.m
- .m 에서 과업 특성 파악 => 과업 list 작성 => R code

실습 2. Matlab => R

- SGD와 Batch 비교
- SGDvsBatch.m => SGDvsBatch.R

SGDvsBatch.m

```
clear all

X=[0 0 1;
  0 1 1;
  1 0 1;
  1 1 1;
  ];

D=[0
  0
  1
  1];

E1=zeros(1000,1);
E2=zeros(1000,1);

W1=2*rand(1,3)-1;
W2=W1;

for epoch = 1:10000 %train
  W1=Deltasgd(W1, X, D);
  W2=Deltabatch(W2, X, D);

  es1=0;
  es2=0;
  N=4;

  for k = 1:N
    x=X(k,:);
    d=D(k);

    v1=W1*x;
    y1=Sigmoid(v1);
    es1=es1+(d-y1)^2;

    v2=W2*x;
    y2=Sigmoid(v2);
    es2=es2+(d-y2)^2;
  end

  E1(epoch)=es1/N;
  E2(epoch)=es2/N;

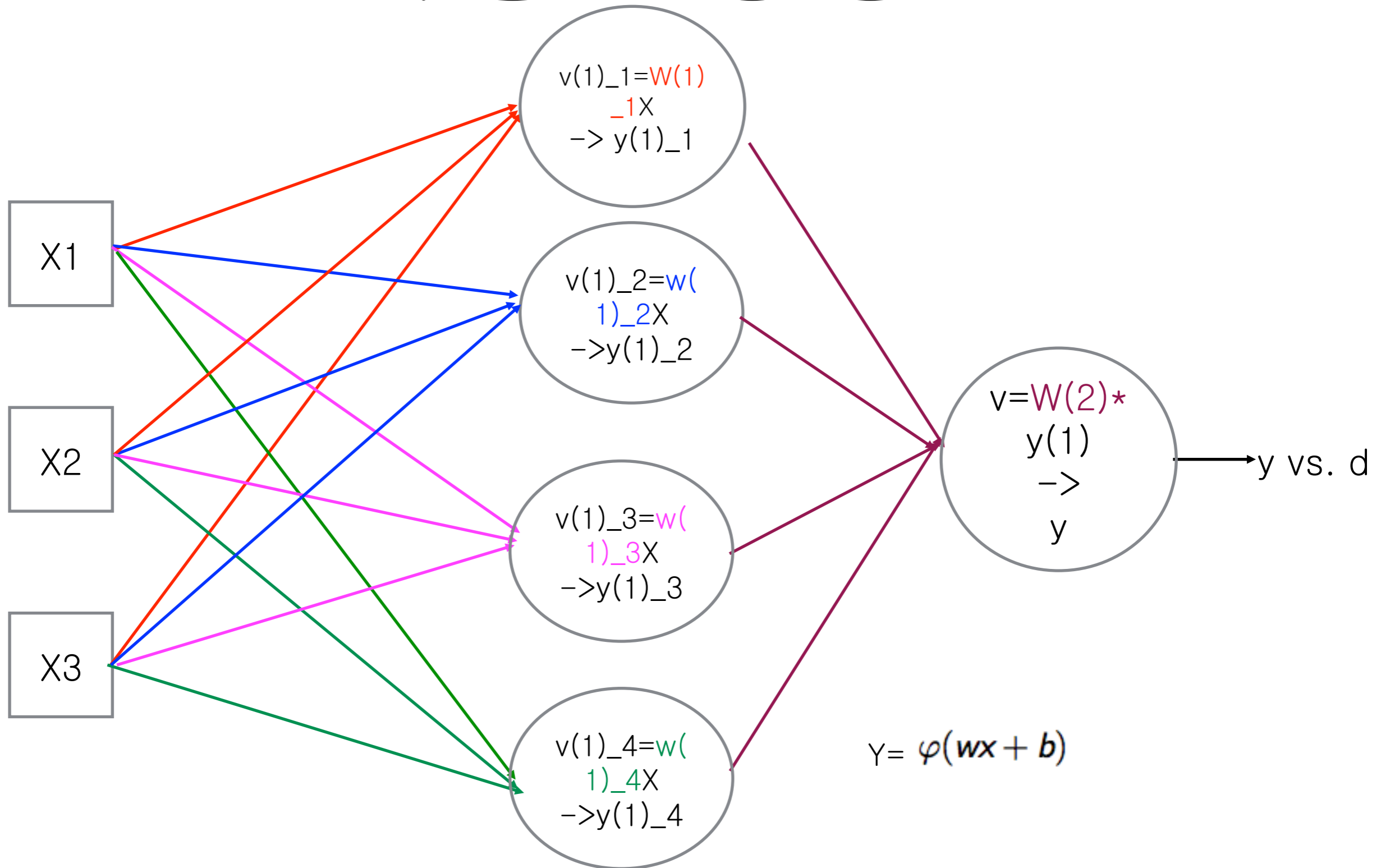
end

plot(E1,'r')
hold on
plot (E2,'b:')
xlabel( 'Epoch')
ylabel('Ave Training Error')
legend('SGD','Batch')
```

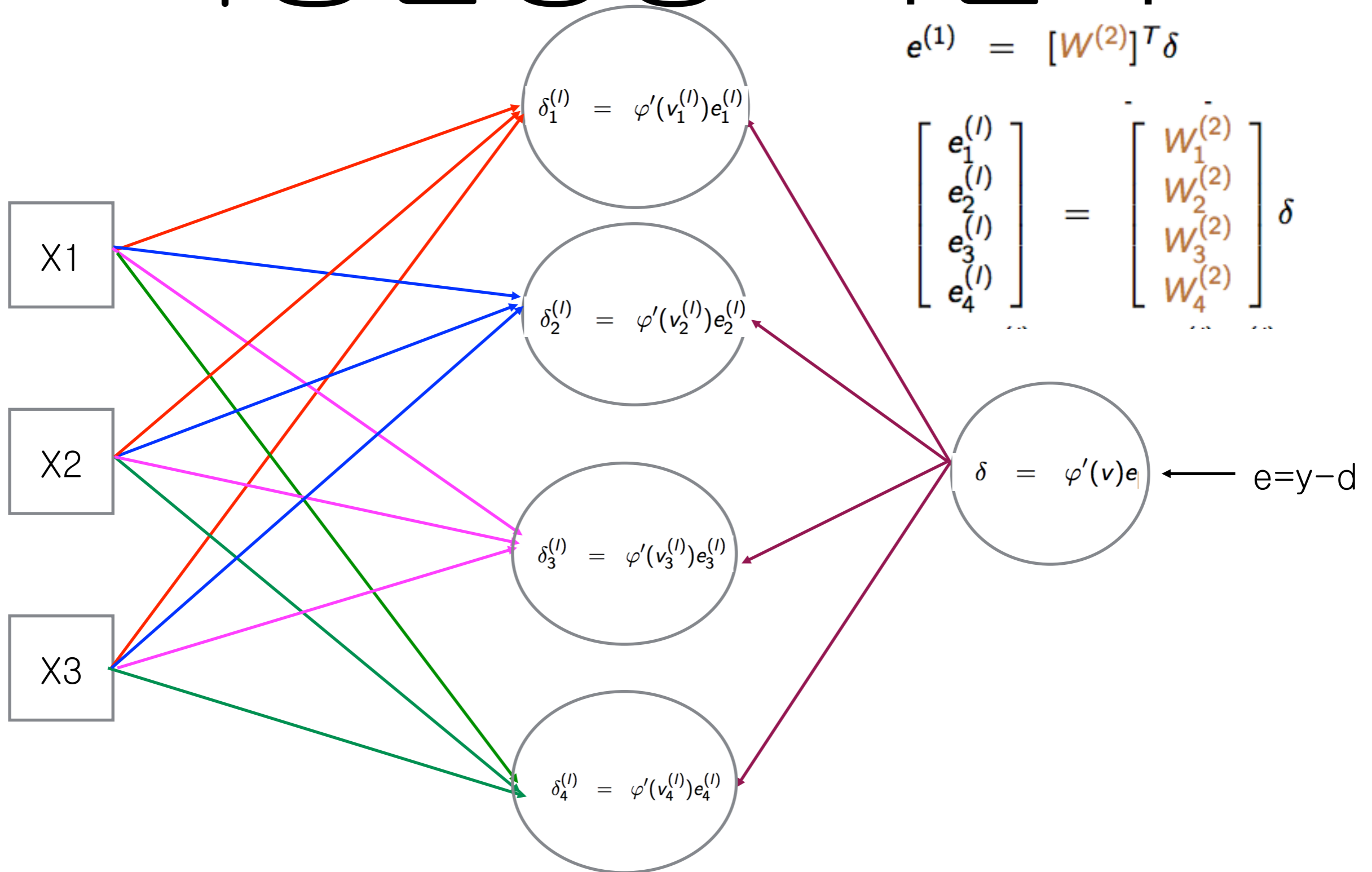
딥러닝 첫걸음

3. 다층 신경망의 학습

다층신경망



다층신경망: 역전파



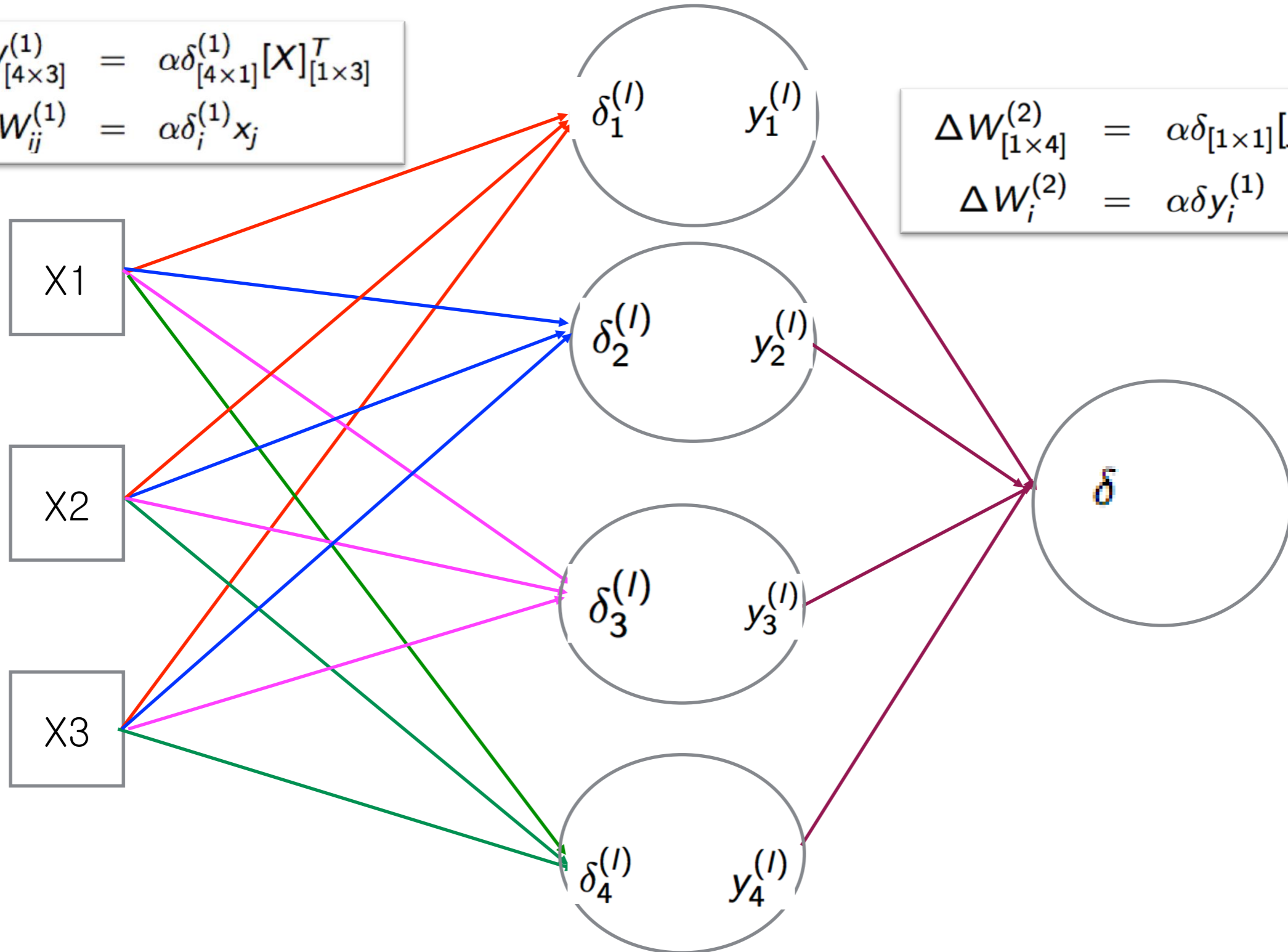
다층신경망: 가중치조정

$$\Delta W_{[4 \times 3]}^{(1)} = \alpha \delta_{[4 \times 1]}^{(1)} [X]_{[1 \times 3]}^T$$

$$\Delta W_{ij}^{(1)} = \alpha \delta_i^{(1)} x_j$$

$$\Delta W_{[1 \times 4]}^{(2)} = \alpha \delta_{[1 \times 1]} [y^{(1)}]_{[1 \times 4]}^T$$

$$\Delta W_i^{(2)} = \alpha \delta y_i^{(1)}$$



다층신경망 학습

STEP 1 가중치 초기화

$$W_{[4 \times 3]}^{(1)} = \begin{bmatrix} w_{11}^{(1)} & w_{12}^{(1)} & w_{13}^{(1)} \\ w_{21}^{(1)} & w_{22}^{(1)} & w_{23}^{(1)} \\ w_{31}^{(1)} & w_{32}^{(1)} & w_{33}^{(1)} \\ w_{41}^{(1)} & w_{42}^{(1)} & w_{43}^{(1)} \end{bmatrix} \quad W_{[1 \times 4]}^{(2)} = [w_1^{(2)}, w_2^{(2)}, w_3^{(2)}, w_4^{(2)}]$$

STEP 2 입력데이터 → 결과

1. 입력층

$$X_{[3 \times 1]} = [x_1, x_2, x_3]^T$$

2. 은닉층

$$v_{[4 \times 1]}^{(1)} = W_{[4 \times 3]}^{(1)} X_{[3 \times 1]}$$

$$y_{[4 \times 1]}^{(1)} = \varphi(v^{(1)})$$

$$v_{[1 \times 1]}^{(l+1)} = W_{[1 \times 4]}^{(l+1)} y_{[4 \times 1]}^{(l)}$$

$$y_{[1 \times 1]}^{(l+1)} = \varphi(v^{(l+1)})$$

3. 출력층

$$v_{[1 \times 1]} = W_{[1 \times 4]}^{(L)} y_{[4 \times 1]}^{(L-1)}$$

$$y_{[1 \times 1]} = \varphi(v)$$

다층신경망 학습 (2)

STEP3 오차, δ

1. 출력층

$$\begin{aligned} e &= y - d \\ \delta &= \varphi'(v) e_{[1 \times 1]} \end{aligned}$$

2. 은닉층

$$\begin{aligned} e_{[4 \times 1]}^{(l)} &= [W^{(l+1)}]_{[4 \times 1]}^T \delta_{[1 \times 1]}^{(l+1)} \\ \delta_{[4 \times 1]}^{(l)} &= \text{Diag}[\varphi'(\hat{v}^{(l)})]_{[4 \times 1]} [4 \times 4] e_{[4 \times 1]}^{(l)} \end{aligned}$$

STEP4 가중치조정

$$\begin{aligned} \Delta W_{i,j}^{(l)} &= \alpha \delta_i^{(l)} y_j^{(l-1)} \\ \Delta W_{[1 \times 4]}^{(L)} &= \alpha \delta_{[1 \times 1]}^{(L)} [y^{(L-1)}]_{[1 \times 4]}^T \\ \Delta W_{[4 \times 3]}^{(l)} &= \alpha \delta_{[4 \times 1]}^{(l)} [X]_{[1 \times 3]}^T \\ W'^{(l)} &= W^{(l)} + \Delta W^{(l)} \end{aligned}$$

training function: BackpropXOR.m

4.가중치 조정

```
function [W1 W2] =  
BackpropXOR(W1,W2, X,D)  
alpha =0.9;  
N=4;  
for k=1:N  
    % Load data. Single obs.  
    x=X(k,:);  
    d=D(k);  
2. 입력 데이터 => 결과  
    % generate outputt  
    %% Layer 1  
    v1=W1*x;  
    y1=Sigmoid(v1);  
    %% Layer 2  
    v=W2*y1;  
    y=Sigmoid(v);  
3. Delta, error  
    % generate error and delta  
    %% Layer 2  
    e=d-y;  
    delta=y.*(1-y).*e;  
    %% Layer 1  
    e1=W2'*delta;  
    delta1=y1.*(1-y1).*e1;
```

```
generate weight adjustment  
%% Layer 1  
dW1 = alpha*delta1*x';  
W1=W1+dW1;  
%% Layer 2  
dW2 = alpha*delta*y1';  
W2=W2+dW2;  
end  
End
```

TestbackpropXOR .m

```
clear all
```

```
X=[0, 0, 1; 0, 1, 1; 1, 0, 1; 1, 1, 1];  
D=[0,1,1,0];
```

1. 가중치 초기화

```
W1=2*rand(4,3)-1;
```

```
W2=2*rand(1,4)-1;
```

2. 학습

```
for epoch=1:1000000  
    [W1 W2]=BackpropXOR(W1,W2,X,D);  
    %W=DeltasgdM(W,X,D);  
end  
y1=Sigmoid(X*W1');  
y=Sigmoid(y1*W2')
```

3. 추정

```
N=4;  
for k=1:N
```

```
    x=X(k,:);  
    v1=W1*x;  
    y1=Sigmoid(v1);  
    v=W2*y1;  
    y=Sigmoid(v)  
end
```

실습 . Matlab => R

- TestbackpropXOR.m
- BoxpropXOR.m

- .m 에서 과업 특성 파악 => 과업 list 작성 => R code

딥러닝 첫걸음

3. 다층 신경망의 학습 - 수렴 속도 제고

수렴 속도 향상 방법

- Momentum : BackPropMmt.m,
TestBackPropMmt.m
- Cross Entropy Loss function: BackPropCE.m,
TestBackPropCE.m
- .m 에서 과업 특성 파악 => 과업 list 작성 => R
code

Momentum: 가중치조정 방식

$$\begin{aligned}\Delta W_{ij}^{(l)} &= \alpha \delta_i^{(l)} y_j^{(l-1)} \\ W_{ij}^{\prime(l)} &= W_{ij}^{(l)} + \Delta W_{ij}^{(l)} \\ &\Rightarrow \\ \Delta W_{ij}^{(l)} &= \alpha \delta_i^{(l)} y_j^{(l-1)} \\ m_{ij}^{(l)} &= \Delta W_{ij}^{(l)} + \beta m_{ij,(-1)}^{(l)} \\ W_{ij}^{\prime(l)} &= W_{ij}^{(l)} + m_{ij}^{(l)} \\ m_{ij,(-1)}^{(l)} &= m_{ij}^{(l)}\end{aligned}$$

실습 . Matlab => R

- TestbackpropMmt.m
- BaxpropMmt.m
- .m 에서 과업 특성 파악 => 과업 list 작성 => R code

BackpropMmt.m

```
function [W1 W2] = BackpropMmt(W1,W2,
X,D)
alpha =0.9;
beta=0.9;
mmt1=zeros(size(W1));
mmt2=zeros(size(W2));
N=4;
for k=1:N
    % Load data. Single obs.
    x=X(k,:);
    d=D(k);

    % generate outputt
    %% Layer 1
    v1=W1*x;
    y1=Sigmoid(v1);
    %% Layer 2
    v=W2*y1;
    y=Sigmoid(v);
    % generate error and delta

    %% Layer 2
    e=d-y;
    delta=y.*(1-y).*e;
    %% Layer 1
    e1=W2'*delta;
    delta1=y1.*(1-y1).*e1;
    % generate weight adjustment
    %% Layer 1
    dW1 = alpha*delta1*x';
    mmt1=dW1+beta*mmt1;
    W1=W1+mmt1;
    %% Layer 2
    dW2 = alpha*delta*y1';
    mmt2=dW2+beta*mmt2;
    W2=W2+mmt2;
end
end
```

TestbackpropMmt.m

```
clear all

X=[0, 0, 1; 0, 1, 1; 1, 0, 1; 1, 1, 1];
D=[0,1,1,0];
W1=2*rand(4,3)-1;

W2=2*rand(1,4)-1;
%W1=0.0001*W1
%W2=0.0001*W2
for epoch=1:10000
%[W1 W2]=BackpropXOR(W1,W2,X,D);
[W1 W2]=BackpropMmt(W1,W2,X,D);
%W=DeltasgdM(W,X,D);
end
y1=Sigmoid(X*W1');
y=Sigmoid(y1*W2')

N=4;
for k=1:N

x=X(k,:);
v1=W1*x;
y1=Sigmoid(v1);
v=W2*y1;

y=Sigmoid(v)
end
```

Cross entropy loss function

$$J = \frac{1}{2}(d - y)^2 \quad \text{SSE: Sum of Squared Residual}$$

$$J = -d \ln(y) - (1 - d) \ln(1 - y) \quad \text{CE: Cross Entropy}$$

- Cross Entropy를 사용하면 출력층의 delta 산출방식이 변화

$$\begin{array}{l} e = y - d \\ \delta = \varphi'(v)e \end{array} \Rightarrow \begin{array}{l} e = y - d \\ \delta = e \end{array}$$

$$\begin{aligned}
J &= -d \ln(y) - (1-d) \ln(1-y) && \text{CE: Cross Entropy} \\
\frac{\partial J}{\partial w_i} &= \left[-\frac{d}{y} - (1-d) \frac{-1}{1-y} \right] \frac{\partial y}{\partial w_i} \\
&= \left[\frac{-d(1-y) + y(1-d)}{y(1-y)} \right] \frac{\partial y}{\partial w_i} = - \left[\frac{y-d}{y(1-y)} \right] \frac{\partial y}{\partial w_i} \\
&= - \left[\frac{y-d}{y(1-y)} \right] \varphi'(wx) x_i \\
&= - \left[\frac{y-d}{y(1-y)} \right] y(1-y) x_i = -e x_i
\end{aligned}$$

실습 . Matlab => R

- TestbackpropCE.m
- BackpropCE.m

- .m 에서 과업 특성 파악 => 과업 list 작성 => R code

실습. Matlab => R

- SSE와 CE 비교
- CEvsSEE.m => CEvsSEE. R

BackpropCE.m

```
function [W1 W2] = BackpropCE(W1,W2,
X,D)
alpha =0.9;
N=4;
for k=1:N
    % Load data. Single obs.
    x=X(k,:)' ;
    d=D(k);

    % generate outputt
    %% Layer 1
    v1=W1*x;
    y1=Sigmoid(v1);
    %% Layer 2
    v=W2*y1;
    y=Sigmoid(v);
    % generate error and delta
    %% Layer 2
    e=d-y;
    delta=e;

    %% Layer 1
    e1=W2'*delta;
    delta1=y1.*(1-y1).*e1;
    % generate weight adjustment
    %% Layer 1
    dW1 = alpha*delta1*x';
    W1=W1+dW1;
    %% Layer 2
    dW2 = alpha*delta*y1';
    W2=W2+dW2;
end
end
```

TestBackpropCE.m

```
clear all
```

```
end
```

```
X=[0, 0, 1; 0, 1, 1; 1, 0, 1; 1, 1, 1];
```

```
D=[0,1,1,0];
```

```
W1=2*rand(4,3)-1;
```

```
W2=2*rand(1,4)-1;
```

```
for epoch=1:10000
```

```
  %[W1 W2]=BackpropXOR(W1,W2,X,D);
```

```
  [W1 W2]=BackpropCE(W1,W2,X,D);
```

```
  %W=DeltasgdM(W,X,D);
```

```
end
```

```
%y=Sigmoid(X*W')
```

```
N=4;
```

```
for k=1:N
```

```
  x=X(k,:);
```

```
  v1=W1*x;
```

```
  y1=Sigmoid(v1);
```

```
  v=W2*y1;
```

```
  y=Sigmoid(v)
```

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CEvsSSE.m

```
clear all

X=[0 0 1;
  0 1 1;
  1 0 1;
  1 1 1;
  ];

D=[0
  0
  1
  1];

E1=zeros(1000,1);
E2=zeros(1000,1);

W11=2*rand(4,3)-1;%Cross Entropy
W12=2*rand(1,4)-1;

W21=W11;%SSE
W22=W12;

for epoch = 1:10000 %train
  [W11, W12]=BackpropCE(W11,W12,X, D);
  [W21, W22]=BackpropXOR(W21,W22, X, D);

  es1=0;
  es2=0;
  N=4;

  for k =1:N
    x=X(k,:)'
    d=D(k);

    v1=W11*x;
    y1=Sigmoid(v1);
    v=W12*y1;
    y=Sigmoid(v);
    es1=es1+(d-y)^2;

    v1=W21*x;
    y2=Sigmoid(v1);
    v=W22*y2;
    y=Sigmoid(v);
    es2=es2+(d-y)^2;
  end

  E1(epoch)=es1/N;
  E2(epoch)=es2/N;

end

plot(E1,'r')
hold on
plot (E2,'b:')
xlabel( 'Epoch')
ylabel('Ave Training Error')
legend('Cross Entropy','SSE')
```